Computer Aided Design (CAD)



Lecture 9

Introduction to Simulink (2)

Dr.Eng. Basem ElHalawany

Schedule (Updated 28-10)

| Topics | Estimated Duration (# Lectures) | |
|---|------------------------------------|--|
| Introduction | 1 | |
| Introduction to Matlab Environment | 1 | |
| Matlab Programing (m-files) (1) | 5 | |
| Modeling using Matlab Simulink Tool | 4 (2/4) | |
| Midterm | 7 th Week | |
| Communication Systems Simulation (Applications) | 3 | |
| Introduction to FPGA + Review on Digital Logic/Circuits | 2 | |
| VHDL Modeling Language | 4 | |
| VHDL Application | 2 | |
| Introduction to OPNET Network Simulator | 3 | |
| Course Closeout / Feedback/ project (s) Delivery | 1 | |



The Lecture is based on :

Modeling of Digital Communication Systems Using





Arthur A. Giordano • Allen H. Levesque

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1.8 SENDING DATA TO WORKSPACE

By adding the "To Workspace" block from Simulink Sinks
 The To Workspace block causes the output data from the Sine Wave block to be saved and examined for subsequent use such as plotting.

| | Sink Block Parameters: To Workspace |
|--|--|
| First_Simulak_Model_simout Prist_Simulak_Model_simout Prist_Simulak_Model_simout First_Simulak_Model_simout Image: Simulak_Model_simout Sine Wave Sine Wave Scope | Sink Block Parameters: To Workspace To Workspace Write input to specified timeseries, array, or structure in a workspace. For menu-based simulation, data is written in the MATLAB base workspace. Data is not available until the simulation is stopped or paused. To log a bus signal, use "Timeseries" save format. Parameters Variable name: simout Limit data points to last: inf Decimation: 1 Save format: Timeseries To log a bus signal, use "Limeseries" |
| | Log fixed-point data as a fi object Sample time (-1 for inherited): -1 |



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1.8 SENDING DATA TO WORKSPACE

| | Current Folder | | | | Variables - simout |
|----------------------|---------------------|-----------------------|---------|------|---|
| | Name 🔺 | | | | simout × |
| | Mpps test_for2.m | | | | 1x1 double timeseries |
| | untitled.slx.a | autosave | | | Time series name: |
| | | | | | Time Data:1 |
| | | | | | 0 0 |
| | | | | | 0.2000 0.9511 |
| | | | | | 0.4000 0.5878 |
| | | | | | 0.6000 -0.5878 |
| Orations Timescovics | | | | | 0.8000 -0.9511 |
| Option: Timeseries | | | | | 1 -2.4493e-16 |
| | | | | | 1.2000 0.9511 |
| | Details | | | ^ | 1.4000 0.5878 |
| | Workspace | | | | 1.6000 -0.5878 |
| | Name 🔺 | Value | Min | Max | 1.8000 -0.9511 |
| | imout | 1x1 double timeseries | -0.9511 | 0.95 | Show event table |
| | 🚹 tout | 51x1 double | 0 | 10 | |
| | | | | | Current time: uniform 0 to 10 seconds |
| | | | | | Command Window |
| | | | | | New to MATLAB? Watch this <u>Video</u> , see <u>E</u> |
| 2. 2. | | | | | $f_X >>$ |
| | • | | | • | |
| | | | | | |
| | | | | | |

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1.8 SENDING DATA TO WORKSPACE

Option: Array

| Name | * | | | | simout 🛛 | | | |
|-----------|----------------|---------|-------------|----|---------------|-------------|-------------------------------------|---|
| 🕌 Apps | | | 51x1 double | | | | | |
| test_for | r2.m | | | | 1 | 2 | 3 | Figure 1 |
| | a.six.autosave | | | 1 | 0 | _ | | |
| | | | | 2 | 0.1253 | | | File Edit View Insert Loois Desktop Window Help |
| | | | | 3 | 0.2487 | | | 🗋 🖆 🛃 🎍 🗞 🔍 🤍 🖤 🕲 堤 🖌 • 🗟 🛛 🖽 🖿 🛄 |
| | | | | 4 | 0.3681 | | | |
| | | | | 5 | 0.4818 | | | |
| | | | | 6 | 0.5878 | | | |
| | | | | 7 | 0.6845 | | | |
| | | | | 8 | 0.7705 | | | 0.6 |
| | | | | 9 | 0.8443 | | | 0.4 |
| | | | | 10 | 0.9048 | | | |
| Details | | | ~ | 11 | 0.9511 | | | 0.2 |
| | | | 0 | 12 | 0.9823 | | | 0 7 |
| Workspace | | _ | ۲ | 13 | 0.9980 | | | |
| Name 🔺 | Value | Min | Max | 14 | 0.9980 | | | |
| 🛨 simout | 51x1 double | -0.9980 | 0.9980 | 15 | 0.9823 | | | -0.4 |
| 📩 tout | 51x1 double | 0 | 1 | 16 | 0.9511 | | | -0.6 |
| | | | | | • | | · · · | |
| | | | | Co | mmand Windo | w | _ | -0.8 |
| | | | | ¢ | New to MATL/ | AB? Watch t | this <u>Video</u> , see <u>Exar</u> | |
| | | | | fx | >> plot >> | (tout | ,simout) | |



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1.9 USING MODEL EXPLORER

Model Explorer is a tool available to provide the user with the ability to view, modify or add elements in the Simulink model and workspace variables.
 To open the Model Explorer, select Model Explorer under the View tab in the

Simulink model window.

| 📟 Model Explorer | | and the second | |
|--------------------------|---|--------------------|--|
| File Edit View Tools Add | Help | | |
| 💽 🗀 ½ 🖷 🛍 💥 🖽 📖 |] 🛨 🚳 💿 🕮 🟺 🖌 fx (|) 🔲 📣 📑 📴 🖶 🗃 🖬 | |
| Search: by Name 👻 | Name: | み Search | |
| Model Hierarchy | Column View: Block Dati Column View: Block Dati Name Model Workspace Configuration (Active) Code for untitled Simulink Design Verifier results Advice for untitled Sine Wave | () Filter Contents | Sink Block Parameters: To Workspace To Workspace Write input to specified timeseries, array, or structure in a workspace. For menu-based simulation, data is written in the MATLAB base workspace. Data is not available until the simulation is stopped or paused. To log a bus signal, use "Timeseries" save format. Parameters Variable name: simout |
| | >⊡> Scope | Scope | Limit data points to last: |
| | To Workspace | ToWorkspace | inf |
| | Contents Search | h Besults | Decimation: 1 Save format: Timeseries Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series Image: Comparison of the series |

1.11 Selecting Model Configuration Parameters

In the Simulink model window, pulling down the Simulation tab and selecting Model Configuration Parameters

| Configuration Parameters: untitled/C | onfiguration (Active) | \$ |
|---|---|----|
| Select: Solver Data Import/Export Optimization Diagnostics Hardware Implementation Model Referencing Simulation Target Code Generation HDL Code Gen | Simulation time Start time: 0.0 Stop time: 1 Solver options Type: Fixed-step Fixed-step size (fundamental sample time): auto | |
| | Tasking and sample time options Periodic sample time constraint: Unconstrained Tasking mode for periodic sample times: Auto Image: Automatically handle rate transition for data transfer Image: Automatically handle rate transition for data transfer Image: Higher priority value indicates higher task priority Image: Automatically handle rate transition for data transfer | E |



- simulation start and stop time and
- ✓ choose the solver for the simulation

Simulation: Simulink Solvers

- A dynamic system is simulated by computing its states at successive time steps over a specified time span, using information provided by the model
- This entails repeatedly solving a set of difference or differential equations describing component blocks in the model of the system being simulated
- The process of solving the model at successive time steps is referred to as **simulating** the system that the model represents
- Simulink provides an assortment of solvers, each geared to solving a specific type of model

 The Solver is selected as ode-45, which, in general is the best first choice as a solver for most Simulink models.



1.11 Selecting Model Configuration Parameters

Solver Options:

For both fixed-step and variable-step solvers, the next simulation time is the sum of the current simulation time and the step size.



- With a fixed-step solver, the step size remains constant throughout the simulation
- With a variable-step solver, the step size can vary in an adaptive fashion from step to step to maximize efficiency, while meeting specified error tolerances
- Simulink also provides the choice of continuous versus discrete solvers
 - Continuous solvers use numerical integration to compute a model's continuous states at the current time step
 - Discrete solvers exist primarily to solve purely discrete models. They compute the next simulation time step for a model and each block in the model updates its individual discrete states

- If the model is modified where the Sine Wave block is chosen to have a Samplebased Sine type and a 0.1 s Sample time is entered,
- The model execution will produce a warning message seen at the bottom of the Simulink model.



The model '<u>untitled</u>' does not have continuous states, hence Simulink is using the solver 'FixedStepDiscrete' instead of solver 'ode3'.



Solver Warning Example (2)



➢ Bad resolution

▲ Unable to determine a fixed step size based on the sample times in the model 'untitled', because the model does not have any discrete sample times. Picking a fixed step size of (0.2) based on simulation start and stop times. You can disable this diagnostic by explicitly specifying a fixed step size in the Solver pane of the Configuration Parameters dialog box, or setting the 'Automatic solver parameter selection' diagnostic to 'none' in the Solver group on the Diagnostics pane of the Configuration Parameters dialog box.



Examples (1) Integration and Signals Multiplexing



1.2 Let
$$x(t) = \frac{4}{\pi} \left[\sin(t) + \frac{1}{3}\sin(3t) + \frac{1}{5}\sin(5t) \right].$$

Parameters

a. Develop a Simulink model for x(t) with an included information block. Assume a 10 s simulation time.

| Sing types Time based | Pi untitled1 * | |
|-------------------------------|---|-----------|
| Sine type: Time based | File Edit View Display Diagram Simulation Analysis Code Tools Help | |
| Time (t): Use simulation time | ▶ ← ← ↓ </td <td>» 🕢 🕶 🛗 🕶</td> | » 🕢 🕶 🛗 🕶 |
| Amplitude: | untitled1 | |
| 4/pi | E Pauntitled 1 | |
| Bias: | | |
| 0 | | |
| Frequency (rad/sec): | | |
| 1*2*pi | | |
| Amplitude: | Sine Wave1 | |
| 4/(3*pi) | 4/(5*pi) | |
| Bias: | Bias: | |
| 0 | 0 | |
| Frequency (rad/sec): | Frequency (rad/sec): | |
| 3*2*pi | 5*2*ni | |
| Phase (rad): | Phase (rad): | |
| 0 | • Dr.Eng. Basem ElHalawany | 15 |

| >++> Sum | |
|---|--|
| Tunction Block Parameters: Sum | |
| Add or subtract inputs. Specify one of the following: a) string containing + or - for each input port, for spacer between ports (e.g. ++ - ++) | -5 -5 |
| b) scalar, >= 1, specifies the number of input ports to be summed. When there is only one input port, add or subtract elements over all dimensions or one specified dimension | ••••••••••••••••••••••••••••••••••••••• |
| Main Signal Attributes | |
| Icon shape: round | |
| Sample time (-1 for inherited): | -5 |
| | |
| | -50 1 2 3 4 5 6 7 8 9 10 Time offset: 0 |

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Different Plotting





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Different Plotting



